

```
import time

import picamera

import io

import os

import RPi.GPIO as GPIO

from datetime import datetime

from PIL import Image


camera = picamera.PiCamera()


#Change difference and pixels to adjust sensitivity. Difference is
#a threshold that the pixel must exceed to be counted as a changed pixel
#Pixel says how many pixels must change to count as a detection
difference = 50 #norm is 50
pixels = 100 #norm is 100


width = 1280
height = 960


count = 0
neb = 13
shutter = 15
galvo = 17


settleTime = 40 #Set to 20 for actual experiments
puffNeeded = 1 #1 means that we need to puff
desiredNumberOfTests = 3 #Change this depending on how many tests you want the program to run
testNum = 0
```

```
startTime = 0 #Used for determining the length of the hold
endTime = 0 #Used for determining the length of the hold
arrayOfDurations = [] # Used to store all the durations to get statistical values after the tests are run
log = ""
GPIO.setmode(GPIO.BOARD)
GPIO.setup(neb, GPIO.OUT)
GPIO.setup(shutter, GPIO.OUT)
```

```
def compare():
    camera.resolution = (100, 75)
    stream = io.BytesIO()
    camera.capture(stream, format = 'bmp')
    stream.seek(0)
    im = Image.open(stream)
    buffer = im.load()
    stream.close()
    return im, buffer
```

```
def newimage(width, height):
    time = datetime.now()
    filename = "motion-%04d%02d%02d-%02d%02d%02d.jpg" %(time.year, time.month, time.day,
time.hour, time.minute, time.second)
    camera.resolution = (width, height)
    camera.capture(filename)
    print "Captured %s" % filename
```

```
def puff():
    global neb
```

```
GPIO.output(neb,0)

time.sleep(1)

GPIO.output(neb,1)

return
```

```
def takePic():
```

```
    global shutter

    GPIO.output(shutter, 1)

    time.sleep(2)

    GPIO.output(shutter, 0)

    return
```

```
def startGalvo():
```

```
    GPIO.output(galvo, 1)

    time.sleep(1)

    GPIO.output(galvo, 0)

    return
```

```
def evaluateTest():
```

```
    global log

    global arrayOfDurations

    duration = endTime - startTime

    seconds = duration % 60

    timeInMinutesMinusSeconds = (duration - seconds)/60

    minutes = timeInMinutesMinusSeconds % 60

    hours = (timeInMinutesMinusSeconds-minutes)/60

    arrayOfDurations.append(duration)

    log = log + 'Test #' + str(testNum) + ' ran for ' + str(hours) + ' hours, ' + str(minutes) + ' minutes
and ' + str(round(seconds,0)) + ' seconds \n'
```

```
return
```

```
def getStats():
```

```
    global arrayOfDurations
```

```
    global log
```

```
    maxValue = round(max(arrayOfDurations), 2)
```

```
    minValue = round(min(arrayOfDurations), 2)
```

```
    meanValue = round(sum(arrayOfDurations)/len(arrayOfDurations), 2)
```

```
    statsMessage = str(desiredNumberOfTests) + ' tests have been completed. The longest was ' +  
str(maxValue) + ' seconds and the shortest was ' + str(minValue) + ' seconds with an average time of ' +  
str(meanValue) + ' seconds. \n'
```

```
    finalMessage = '\n \nThe test is done. \n' + statsMessage + log
```

```
    print(finalMessage)
```

```
    return
```

```
image1, buffer1 = compare() #Takes a control image to compare against following images.
```

```
#timestamp = time.time()
```

```
#print 'Do it now!'      #Agitate particles now to allow time for settling. Move to while loop later.
```

```
#puff()
```

```
#time.sleep(20)
```

```
#print 'Times up'      #differences detected now will be counted as a particle trap.
```

```
while testNum < desiredNumberOfTests:
```

```
    #time.sleep(5)
```

```
    #####
```

```
    #   Nebulize
```

```
    #       Wait 5-10 s
```

```
    #####
```

```

print 'Start detection'    #differences detected now will be counted as a particle trap.

if puffNeeded == 1:
    puff()
    print 'Settling'
    time.sleep(40)
    print 'Detecting'
    puffNeeded = 0

image2, buffer2 = compare() #takes second image to compare against the control.

changedpixels = 0           #keeps track of how many pixels have changed beyond
the allowed threshold.

for x in xrange(0, 100):
    for y in xrange(0,75):
        pixdiff = abs(buffer1[x,y][1] - buffer2[x,y][1]) #The [1] signifies the green pixel
only is being compared since it is the most intense
        if pixdiff > difference:
            changedpixels += 1

    if changedpixels > pixels:    #Change code inside statement to change what program does
once it detects trapping

        print 'Particle Trapped'
        startTime = time.time()
        newimage(width, height)
        # start recording
        takePic()

        # start drawing
        #startGalvo()

```

```

image3, buffer3 = compare()

changedpixels = 0                                #keeps track of how many pixels have changed beyond
the allowed threshold.

for x in xrange(0, 100):
    for y in xrange(0,75):
        pixdiff = abs(buffer1[x,y][1] - buffer3[x,y][1]) #The [1] signifies the green pixel
only is being compared since it is the most intense
        if pixdiff > difference:
            changedpixels += 1

while changedpixels > pixels:
    image3, buffer3 = compare()
    changedpixels = 0                                #keeps track of how many pixels have changed
beyond the allowed threshold.
    for x in xrange(0, 100):
        for y in xrange(0,75):
            pixdiff = abs(buffer1[x,y][1] - buffer3[x,y][1]) #The [1] signifies the green
pixel only is being compared since it is the most intense
            if pixdiff > difference:
                changedpixels += 1

endTime = time.time() #takes a picture if enough pixels have changed to be counted
evaluateTest()
testNum = testNum + 1
count += 1
puffNeeded = 1          #Used to get the next particle in there
getStats()
GPIO.cleanup()

```